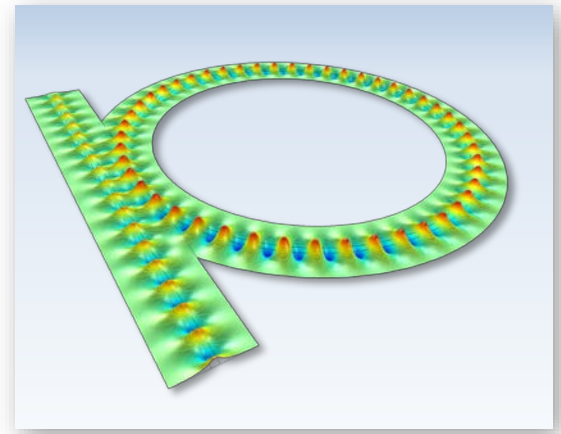
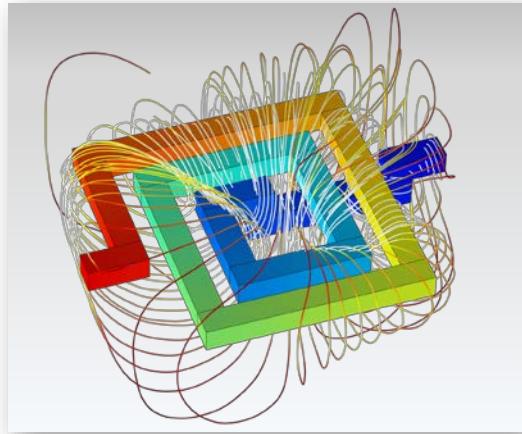
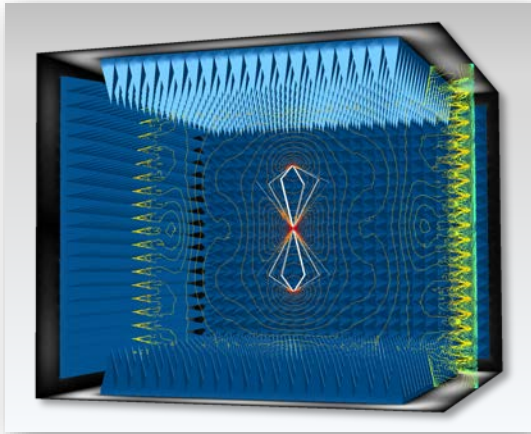


Best Practices in EM Simulation in COMSOL Multiphysics



Presenters

Control the poly-dispersed droplet breakup mode inside a microfluidic flow-focusing device by external electric field

Yuehao Li* and Prof. K. Nandakumar
EPIC Center
Louisiana State University

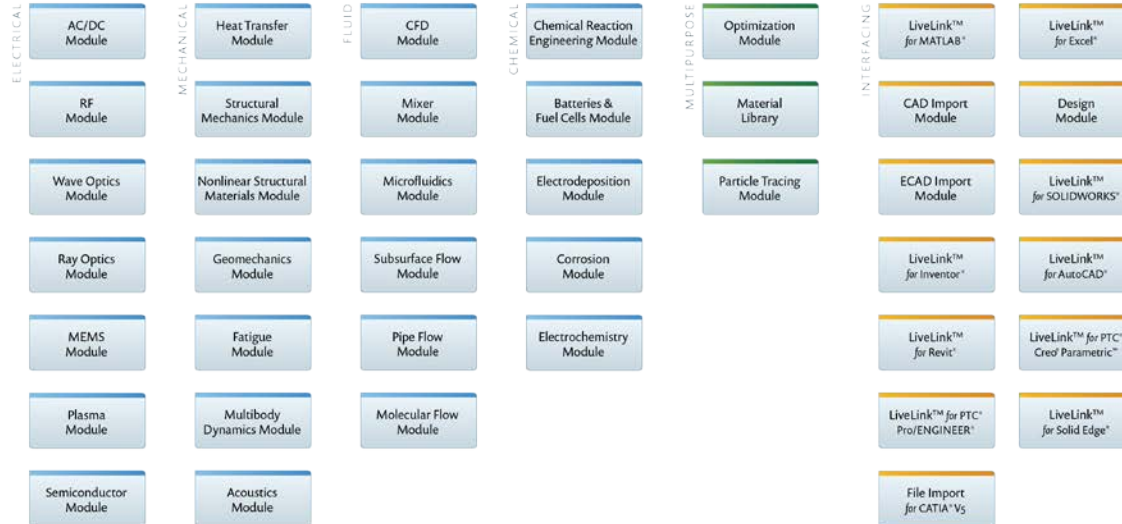
Simulating Plasmon Effect in Nanostructured OLED Cathode Using COMSOL Multiphysics

Leiming Wang
Konica Minolta Laboratory USA Inc.

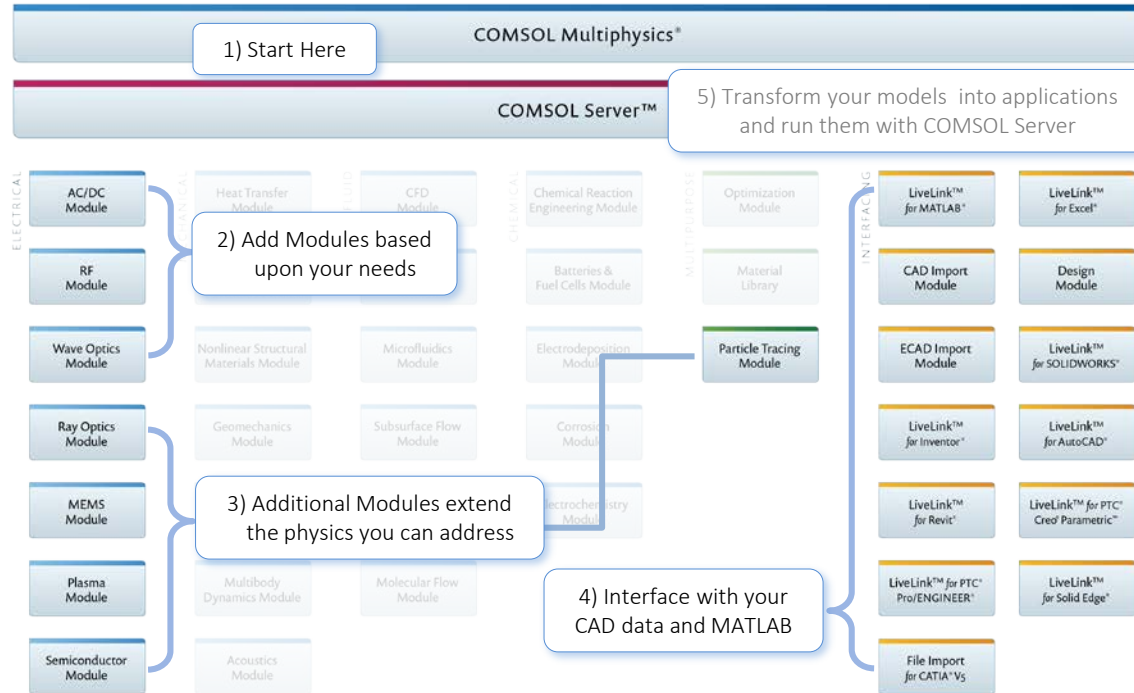
Product Suite – COMSOL® 5.2

COMSOL Multiphysics®

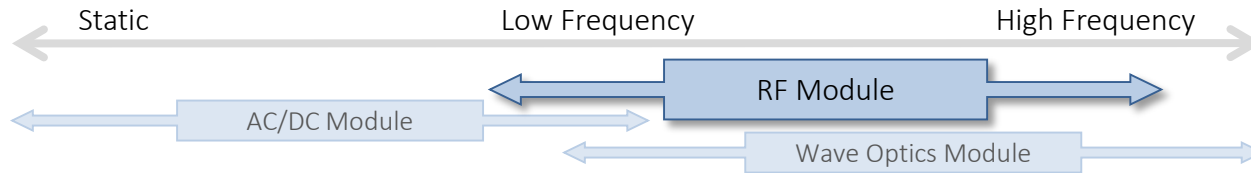
COMSOL Server™



Electromagnetics is Extended by Add-on Modules



Frequency coverage



- What is “high frequency”?
- Linear/nonlinear/dispersive models?

Formulations per Module

COMSOL Multiphysics ¹	RF Module	Wave Optics Module	AC/DC Module
Static Electric Currents Static Joule Heating Electrostatics Magnetic Fields ²	Electromagnetic Waves - Frequency Domain - Time Explicit - Transient Microwave Heating Transmission Line Equations Electrical Circuits	Electromagnetic Waves - Frequency Domain - Time Explicit - Transient - Beam Envelopes Laser Heating	Electric Currents in Solids Electric Currents in Shells Joule Heating Electrostatics Magnetic Fields Induction Heating Magnetic and Electric Fields Magnetic Field Formulation Rotating Machinery Electrical Circuits

¹ Core package contains a reduced set of boundary conditions for these formulations

² 2D and 2D-axisymmetric geometries and static and frequency domain formulations only

Maxwell's Equations

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

- Maxwell-Ampere's law

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

- Faraday's law

$$\nabla \cdot \mathbf{D} = \rho$$

- Gauss' law, electric

$$\nabla \cdot \mathbf{B} = 0$$

- Gauss' law, magnetic

$$\nabla \cdot \mathbf{J} = -\frac{\partial \rho}{\partial t}$$

- Equation of continuity

FAQ

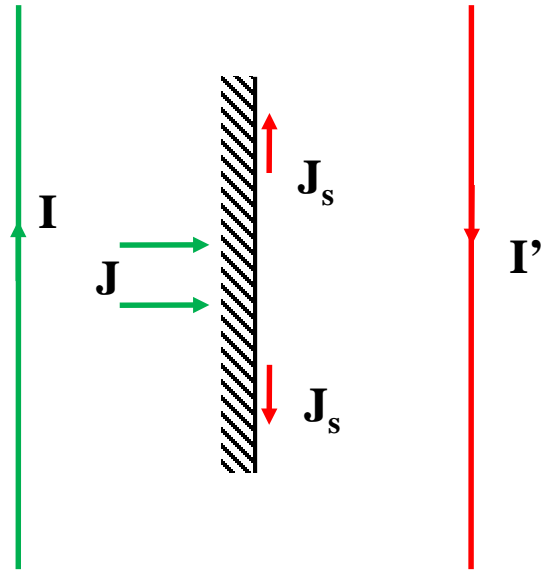
- What is the definition of voltage?
- What is the definition of “ground”?
- On the use of analytical solutions
- Initial conditions for time domain simulations
- Open boundaries, PMLs, radiation conditions

Voltage

- In DC, electric and magnetic fields are one-way coupled:
- $\mathbf{E} = -\nabla V \rightarrow \mathbf{J} = \sigma \mathbf{E} \rightarrow \mathbf{B}$ (Ohm's Law + Ampère's Law)
 - Voltage = *potential difference*
- In AC, the alternating \mathbf{B} field contributes to \mathbf{E} .
Faraday's Law: $\nabla \times \mathbf{E} = -d(\mathbf{B})/dt \Rightarrow \mathbf{E} \neq -\nabla V$
- In AC inductive/EM field modeling “voltage” is not the same as “potential difference”!

“Ground” in EM (inductive) models

Magnetic Insulation
or PEC
 $\mathbf{n} \times \mathbf{A} = 0 \Leftrightarrow \mathbf{n} \cdot \mathbf{B} = 0$
or
“ $\mathbf{n} \times \mathbf{E} = 0$ ”



- Models highly conductive media, with no losses.
- Zero-impedance condition – allows for return currents / induced surface currents
- Used to model “ground planes” and “anti symmetry”

Analytical solutions

Can give artifacts in models:

- Mesh convergent
 - Analytical vs. numerical ports
 - “Discrete divergence” of source currents
- Inconsistent
 - Applicability of Biot-Savart formula
 - Approximations

Initial Conditions

- Computed static solution as IC
 - Nonlinear/iterative solver
- Charge relaxation modeling
 - Consistent initial charges required

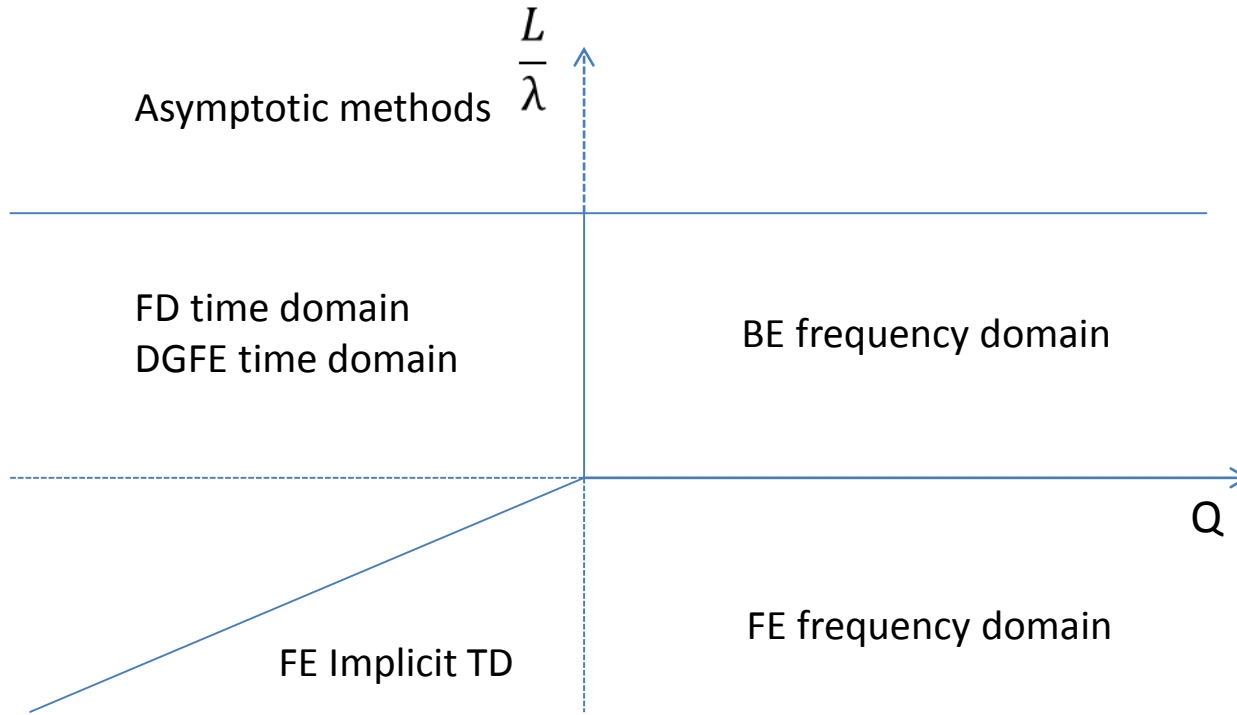
Open boundaries

- Radiation/infinity vs. symmetry boundaries
- Tailoring PMLs
 - Meshing
 - Scaling
 - Advanced methods – Scaling System

Technology in the works

- Nodal discontinuous Galerkin (DG)
 - Time Domain EM Waves
- Integral Equations / Boundary elements
 - Statics and Waves

Methods for EM problems



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