

Simulation and verification of Thomson actuator systems

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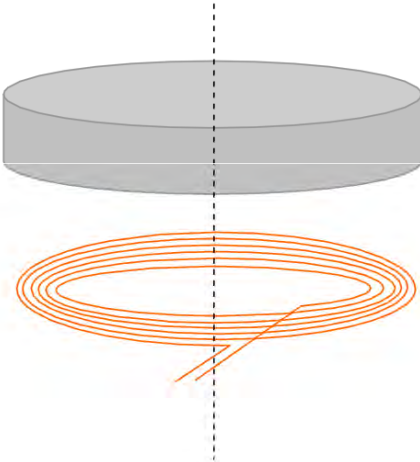
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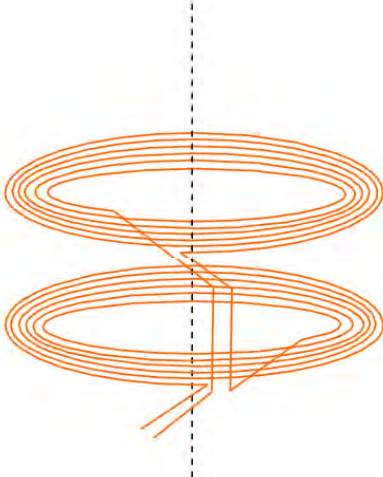
Introduction

- Increased need for high speed actuators
- Diverse applications like: Smart grids, electrical switches, robotics, drilling machinery, etc...
- Thomson Coils (TCs) can exert massive forces within fractions of a millisecond
- It is important to model and simulate (TCs) to design or accurately predict the performance of TC based high speed actuators

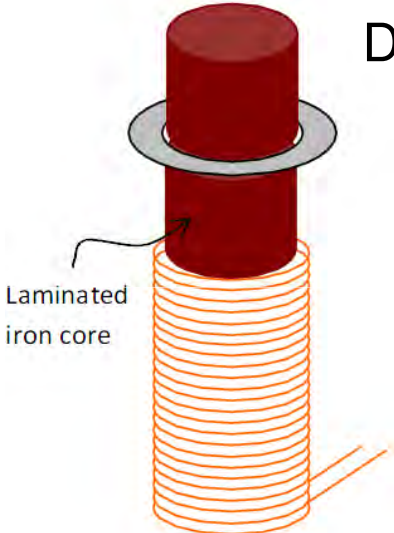
What is a TC?



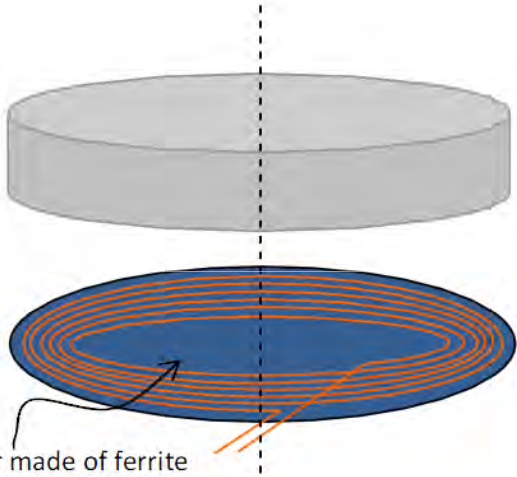
Single sided Thomson Coil



Double sided Thomson coil



Helix- shaped Thomson coil



Single sided Thomson Coil with a concentrator

Theory

$$i_c = I_c \sin(\omega t)$$

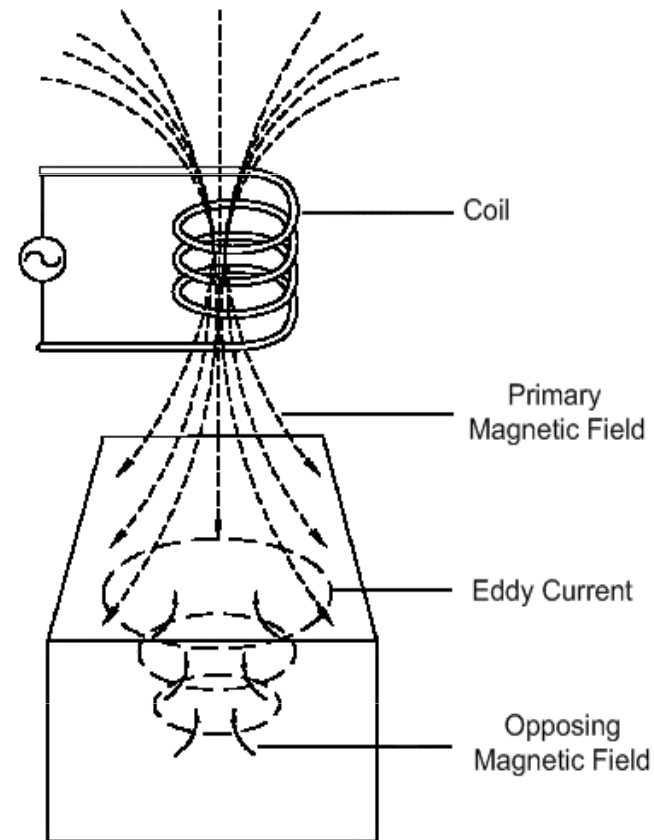
$$B(t) = B_c(r, z) \sin(\omega t)$$

$$B_z = B_z \sin(\omega t)$$

$$B_r = B_r \sin(\omega t)$$

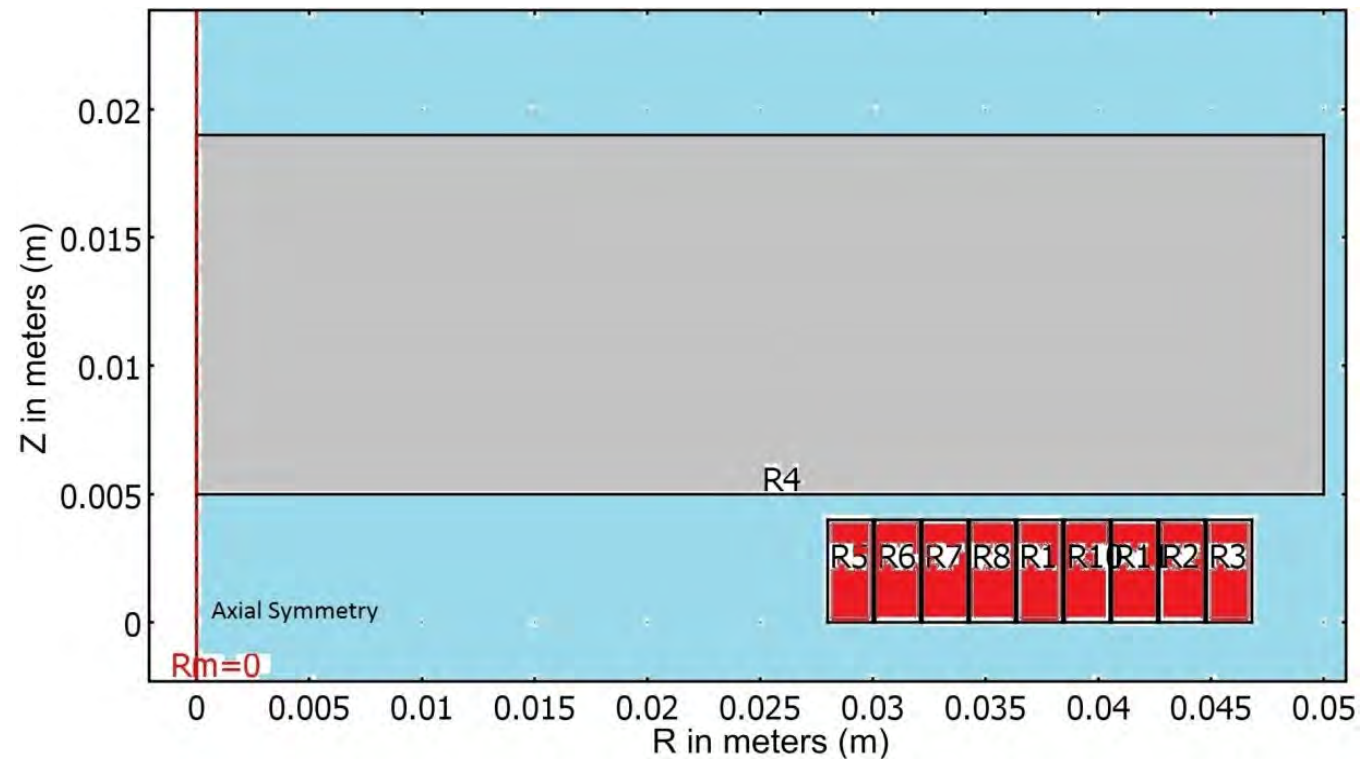
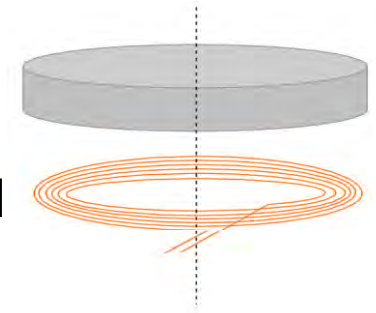
$$F_z = i_\phi B_r$$

$$F_{Total} = ma$$



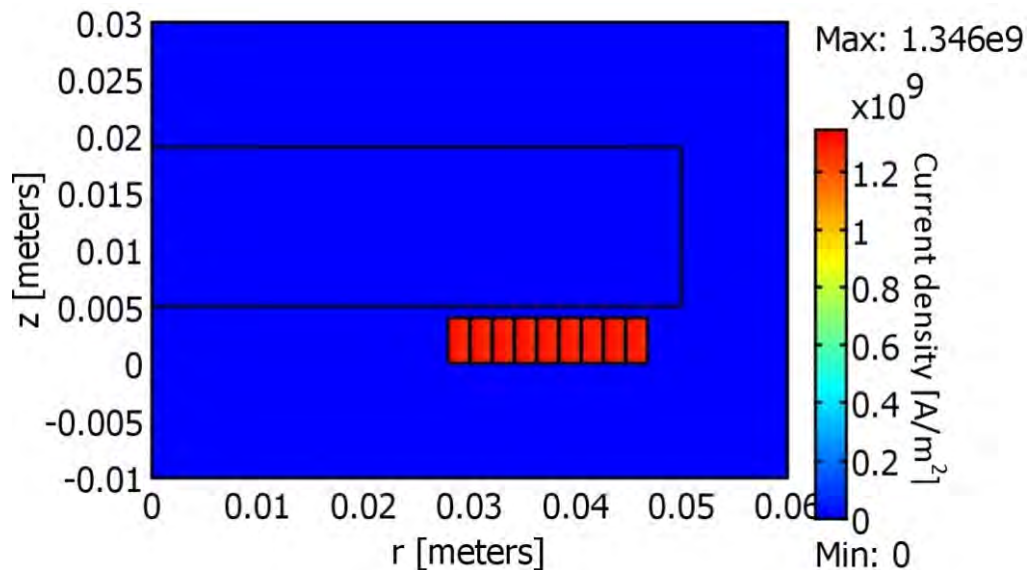
Modelling

- 2D axisymmetric model
- The Aluminum is in silver color, the coil turns are in red surrounding air in light blue

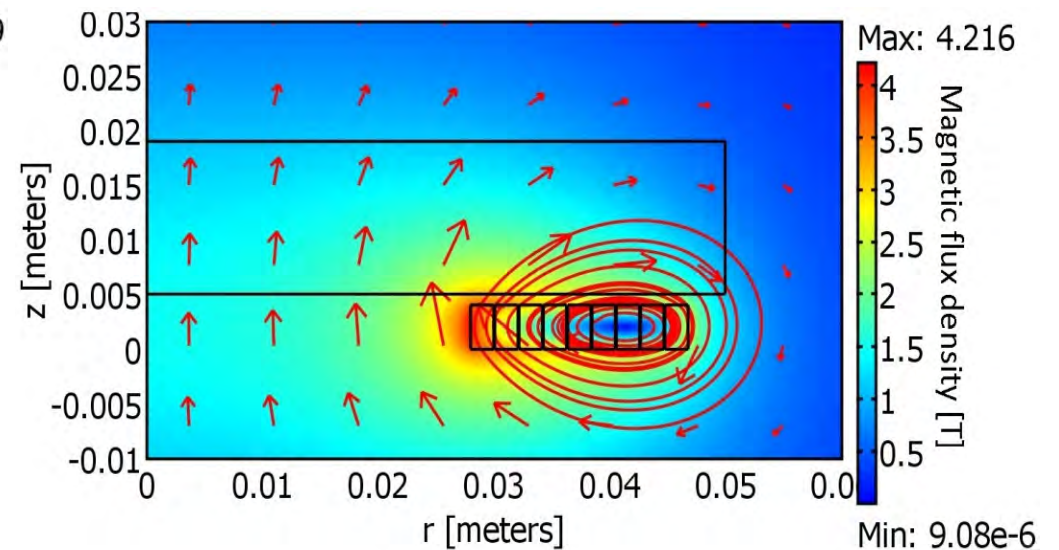


Static model (DC)

- 10kA constant current source connected across the terminals of a TC
- Constant magnetic field will be generated
- No eddy currents are induced in the aluminum disk



Surface: Total Current density [A/m^2]



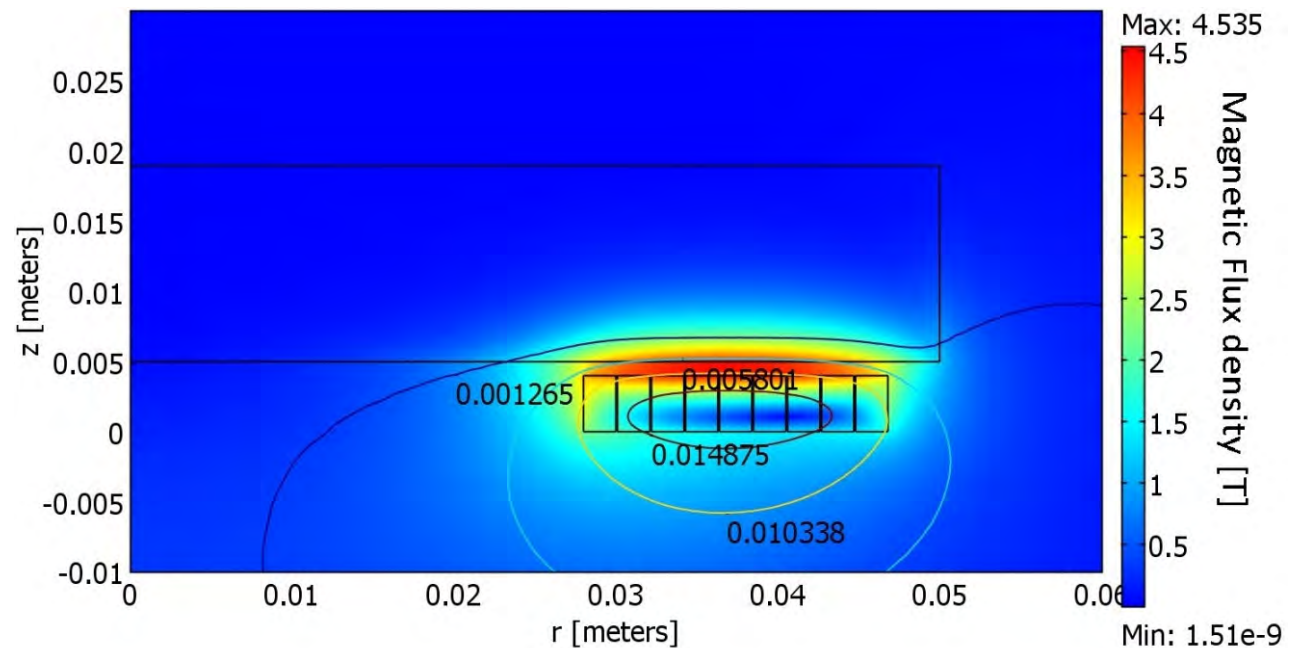
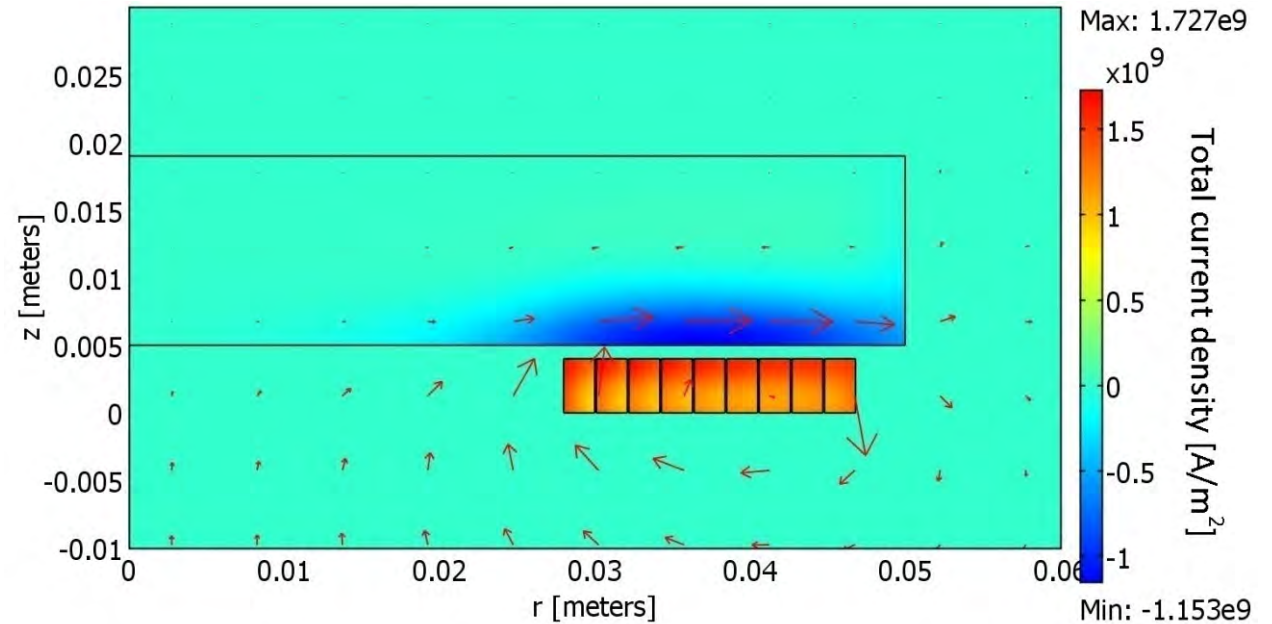
Surface: Magnetic flux density [T]

Contour: Magnetic vector potential [Wb/m]

Arrow: Magnetic flux density

Stationary model (AC)

- Applied current: 10 kA
- Frequency: 1kHz
- Skin effect
- Proximity effect
- The magnetic flux density is concentrated in the air gap region between the coil and the aluminum disk

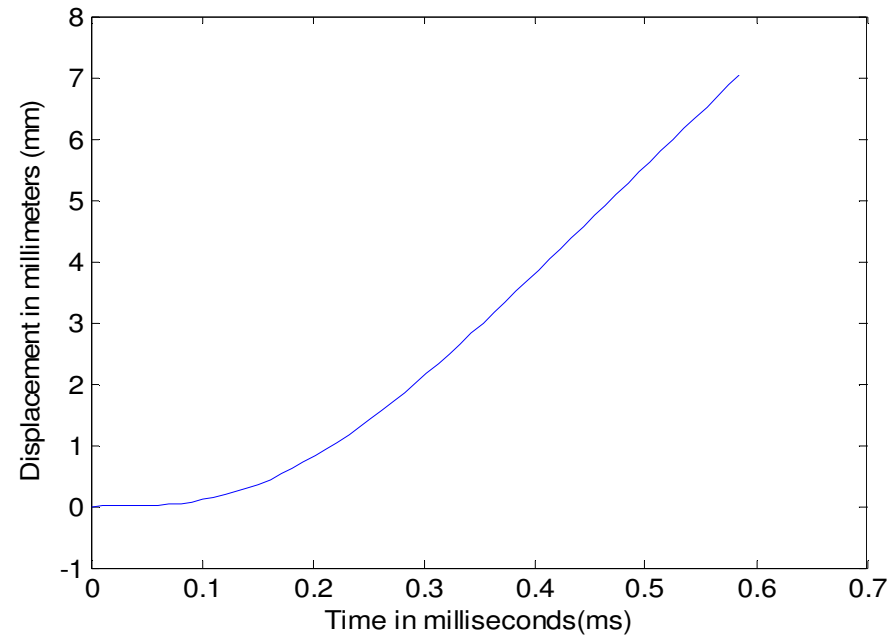
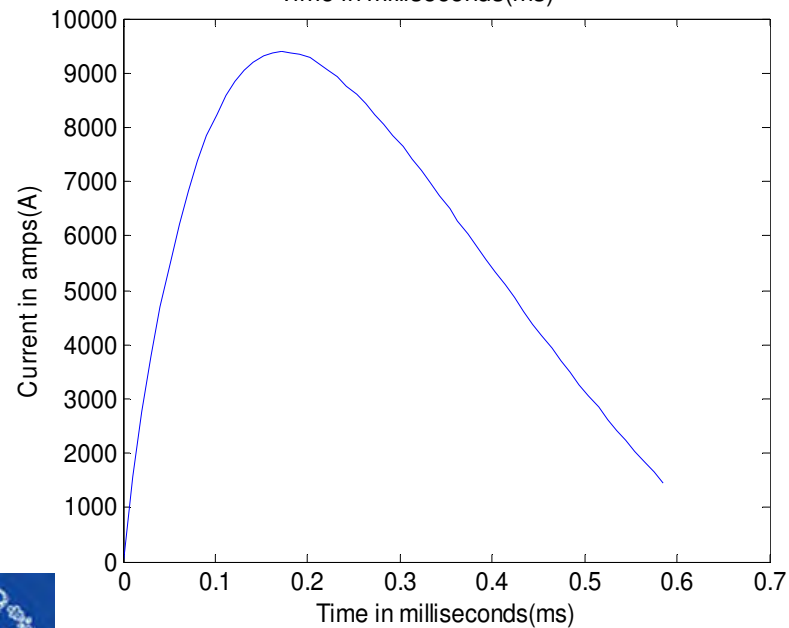
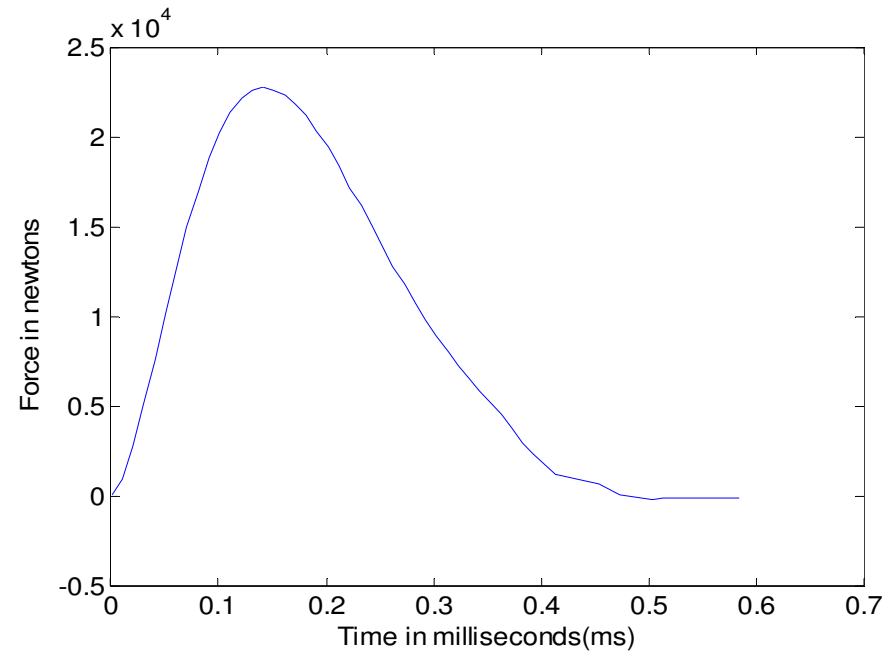
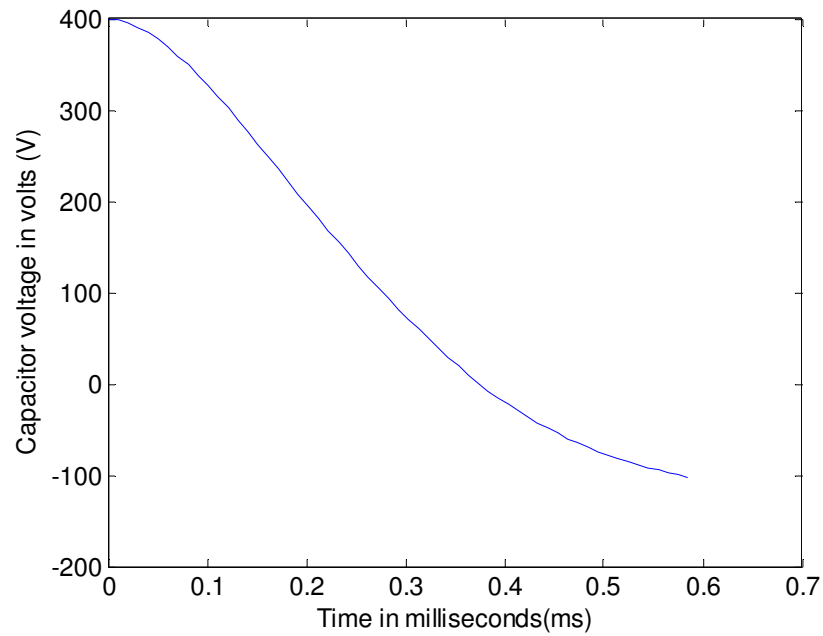


Transient multiphysics model

- The single sided TC is highly dependent on position of the aluminum disk
- As the disk moves away, the inductance, resistance, and induced currents change greatly influencing the exerted force
- A multiphysics model with a moving mesh is indispensable.
- COMSOL modules used: “Azimuthal induction currents”, and “moving mesh (ALE) with dynamic remeshing”.

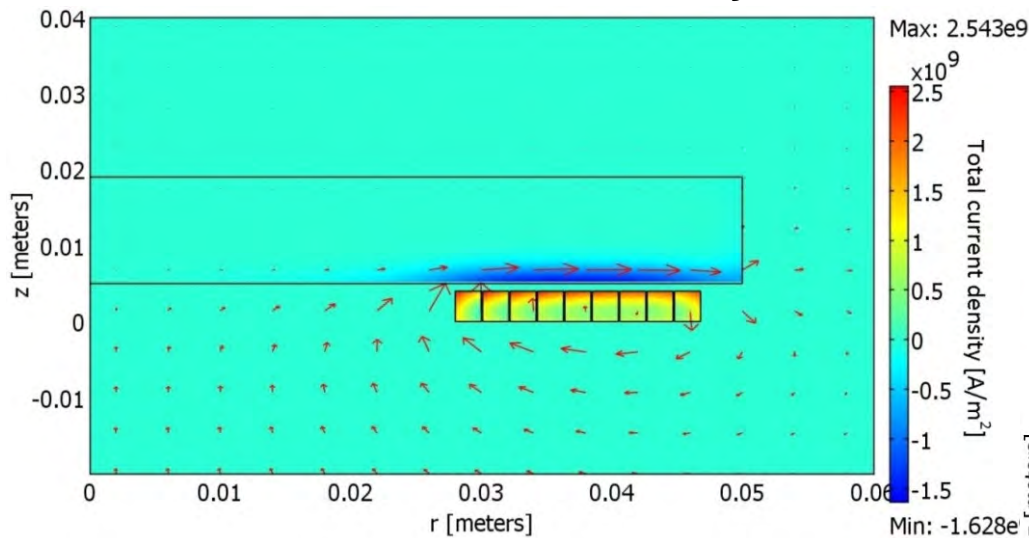
| Setup Characteristics | TC |
|--|------------|
| Capacitor bank | 7 mF |
| Initial voltage | 400 V |
| Al Cross section area in (mm ²) | 50 x 14 |
| Coil cross section area | 2 mm x 4mm |
| Air gap between coil and Al | 1 mm |
| Number of coil turns | 9 |
| Inter-distance coil turns | 0.1 mm |
| Stray resistance | 10 mΩ |
| Stray inductance | 1 μH |

Transient multiphysics model

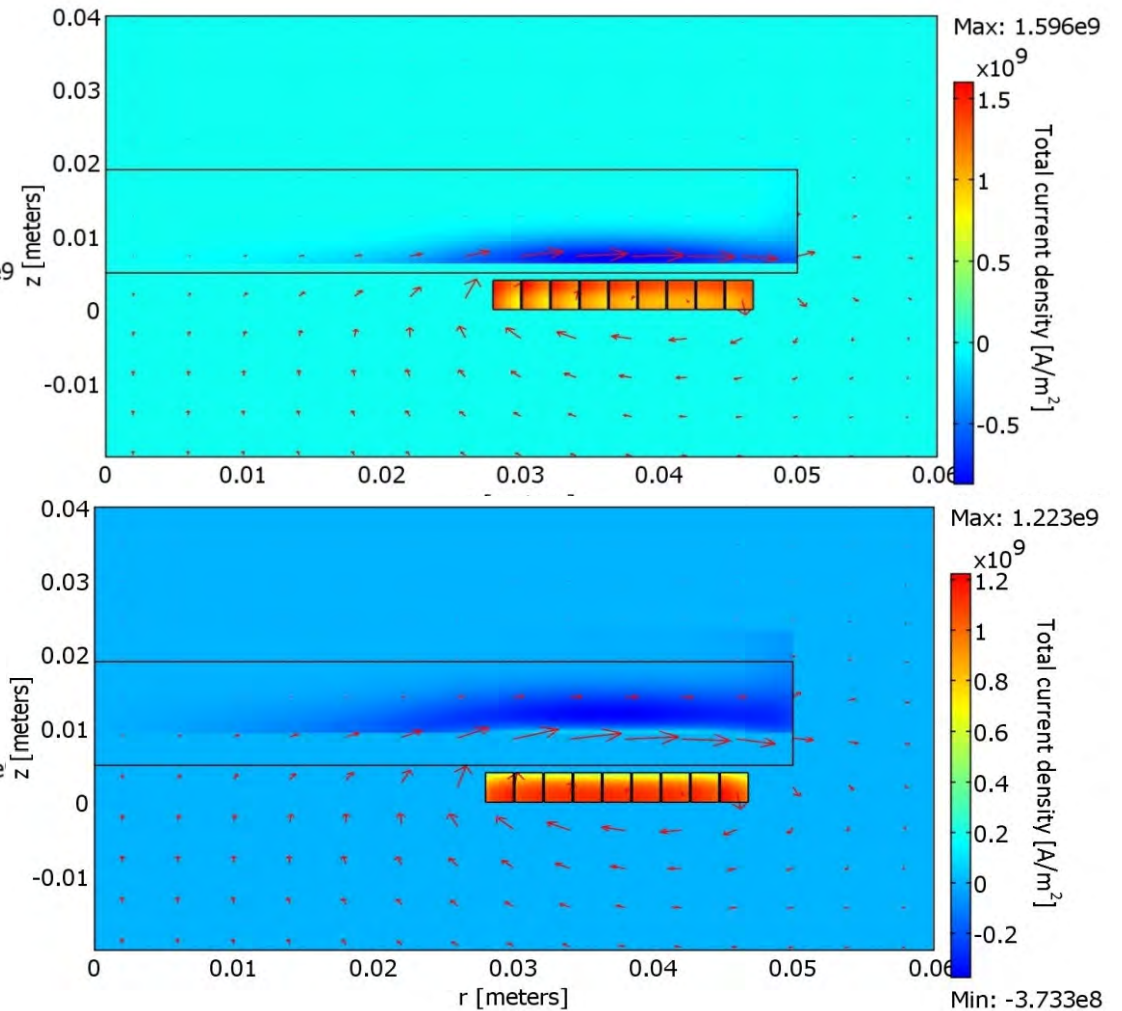


Transient multiphysics model

Time: 0.1ms
Arrow: magnetic field
Surface: Total current density



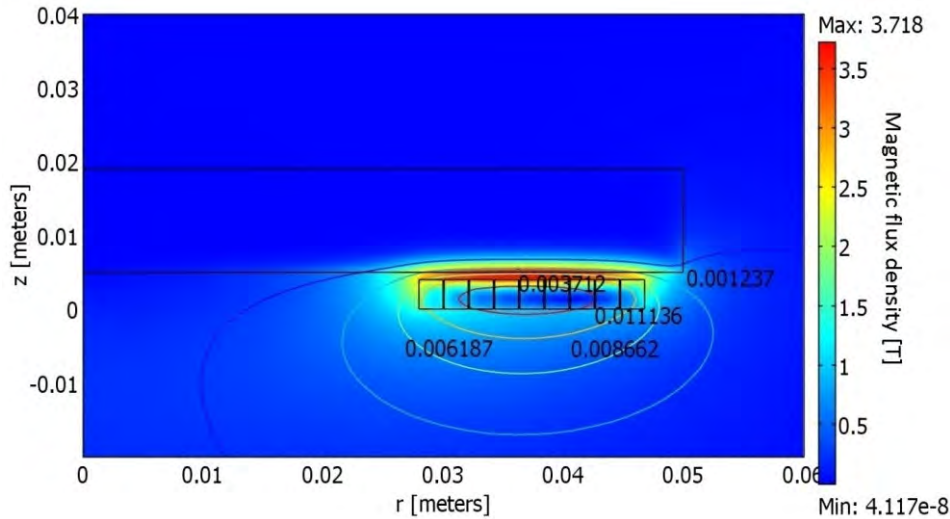
Time: 0.18ms
Arrow: magnetic field
Surface: Total current density



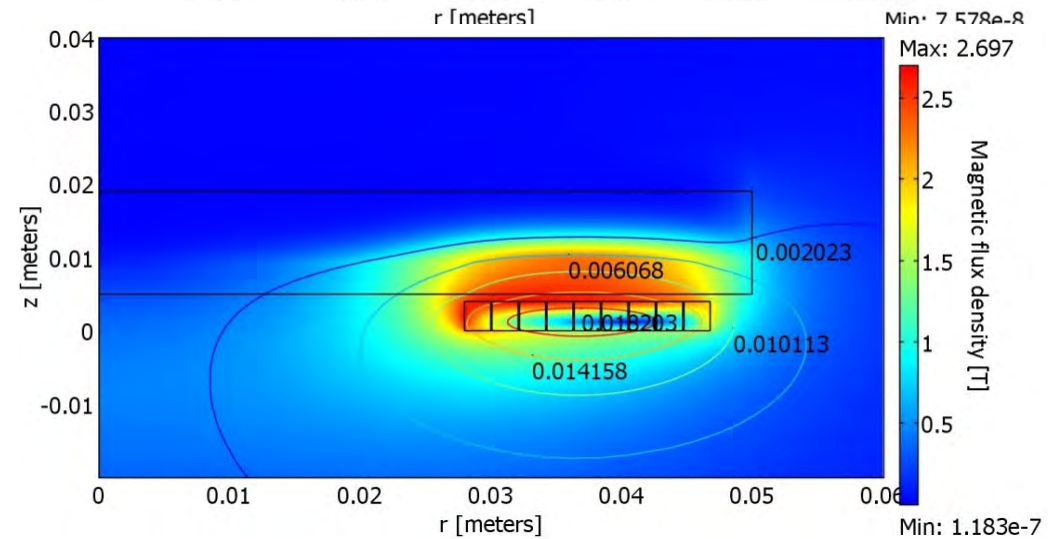
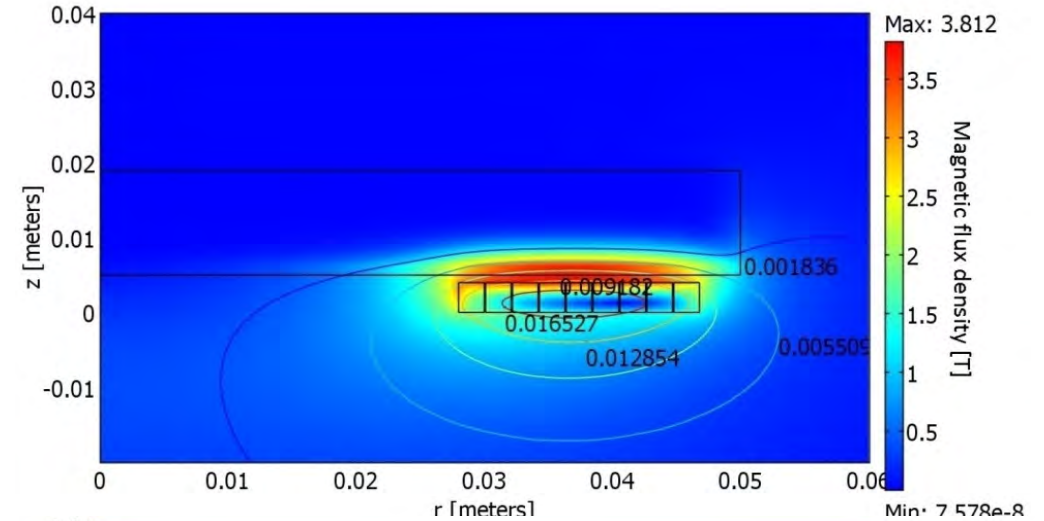
Time: 0.3 ms
Arrow: magnetic field
Surface: Total current density

Transient multiphysics model

Time: 0.1ms
Contour lines: A [Wb/m]
Surface: Magnetic flux density [T]



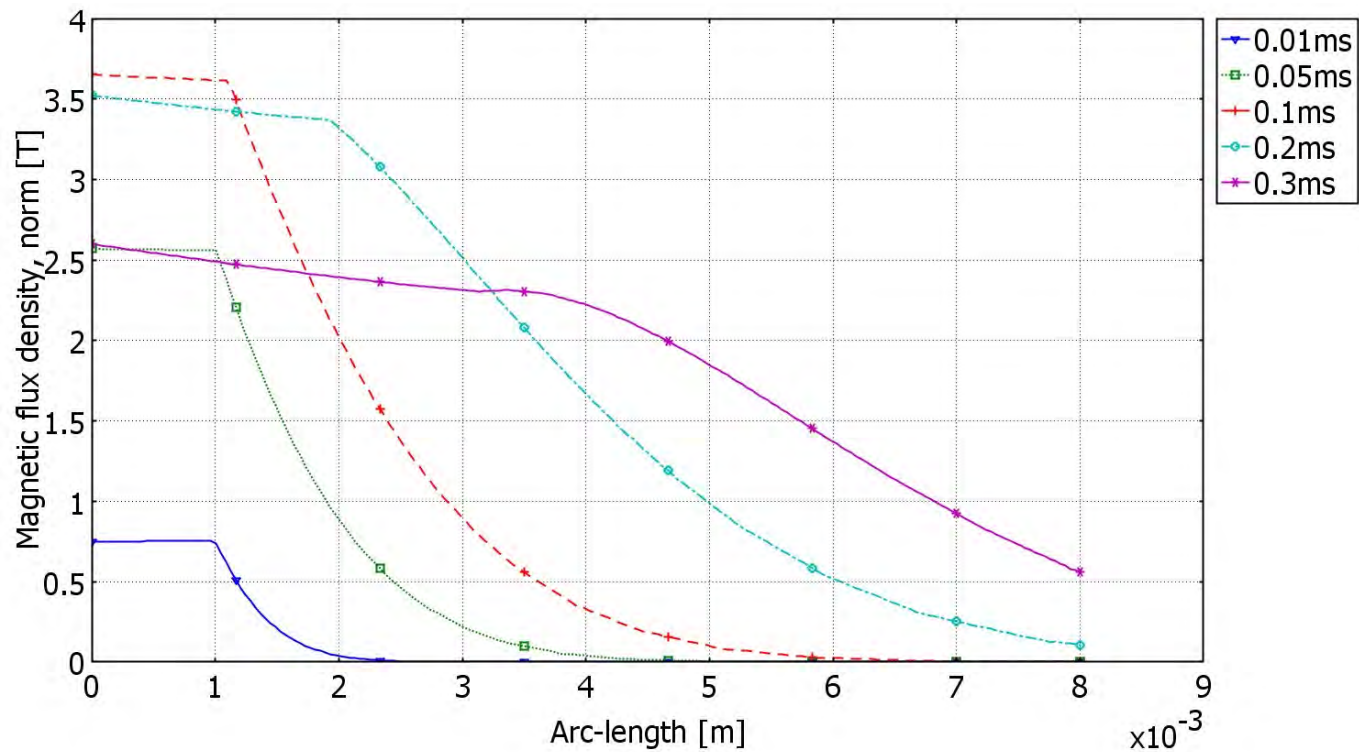
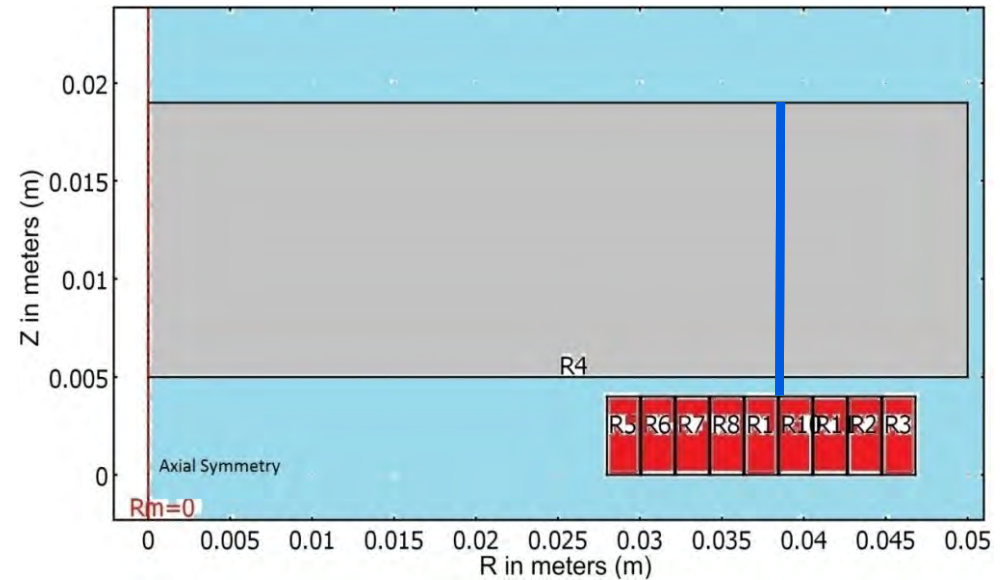
Time: 0.18ms
Contour lines: A [Wb/m]
Surface: Magnetic flux density [T]



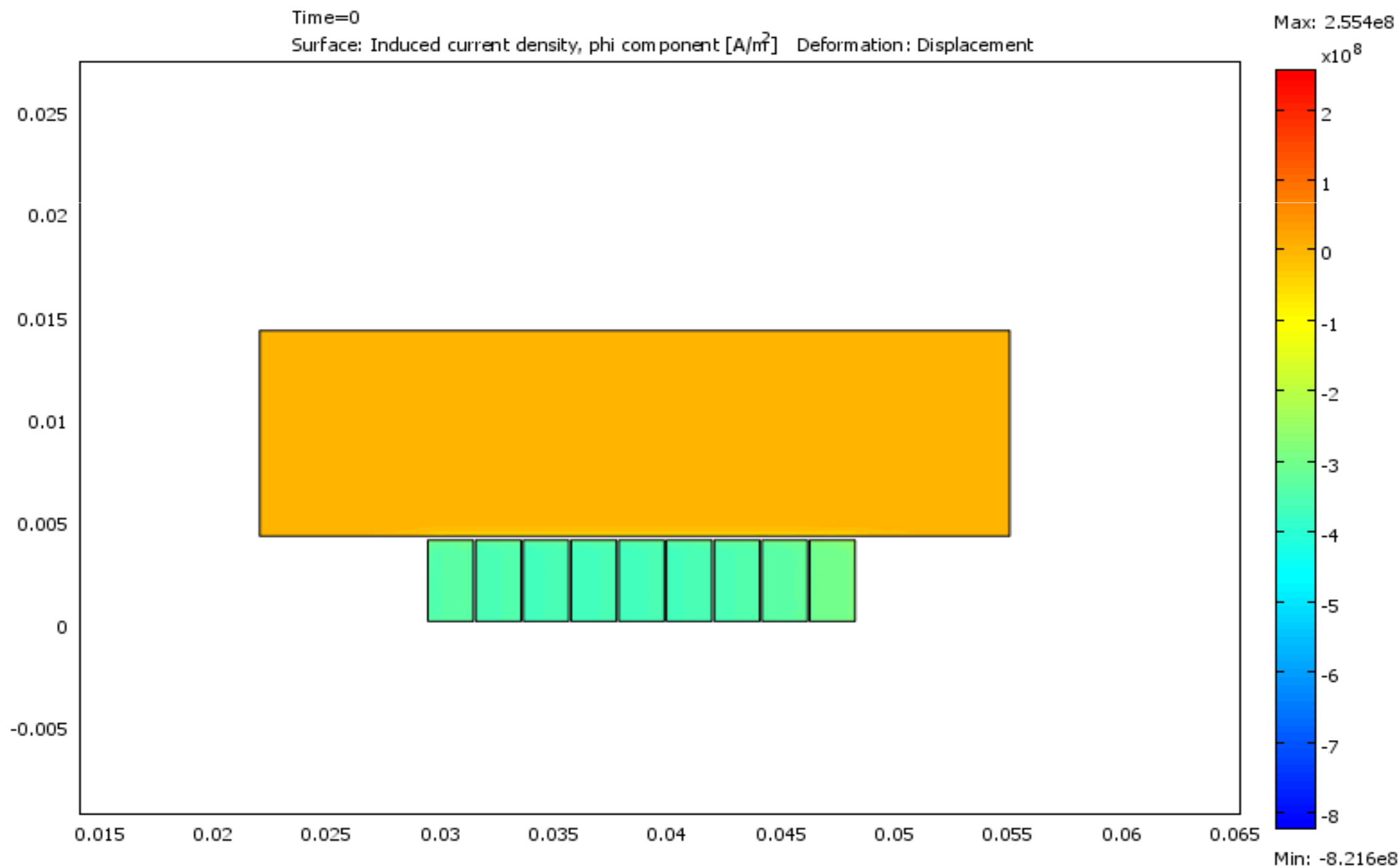
Time: 0.3ms
Contour lines: A [Wb/m]
Surface: Magnetic flux density [T]

Transient multiphysics model

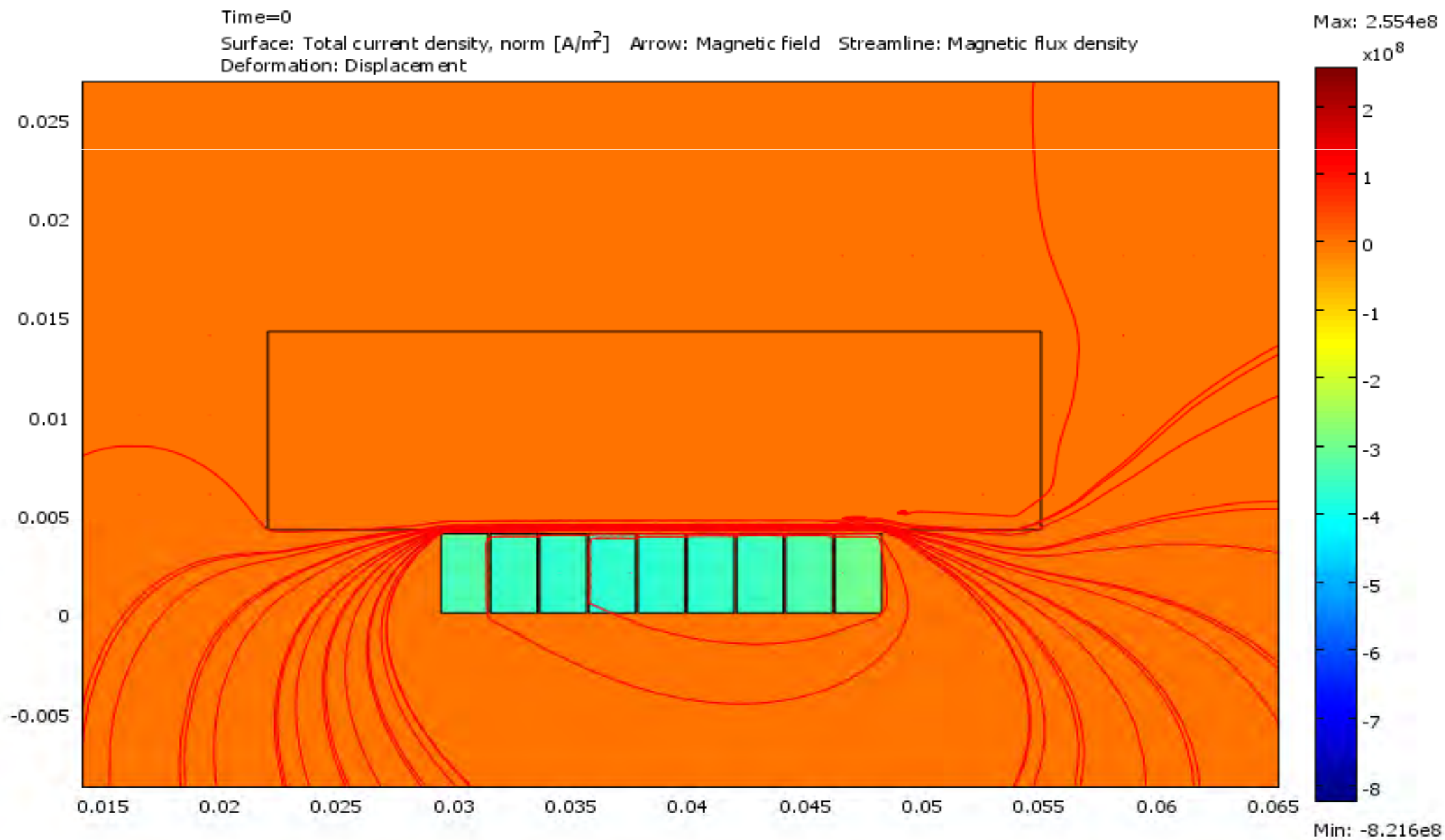
- Penetration depth with respect to time along the blue line



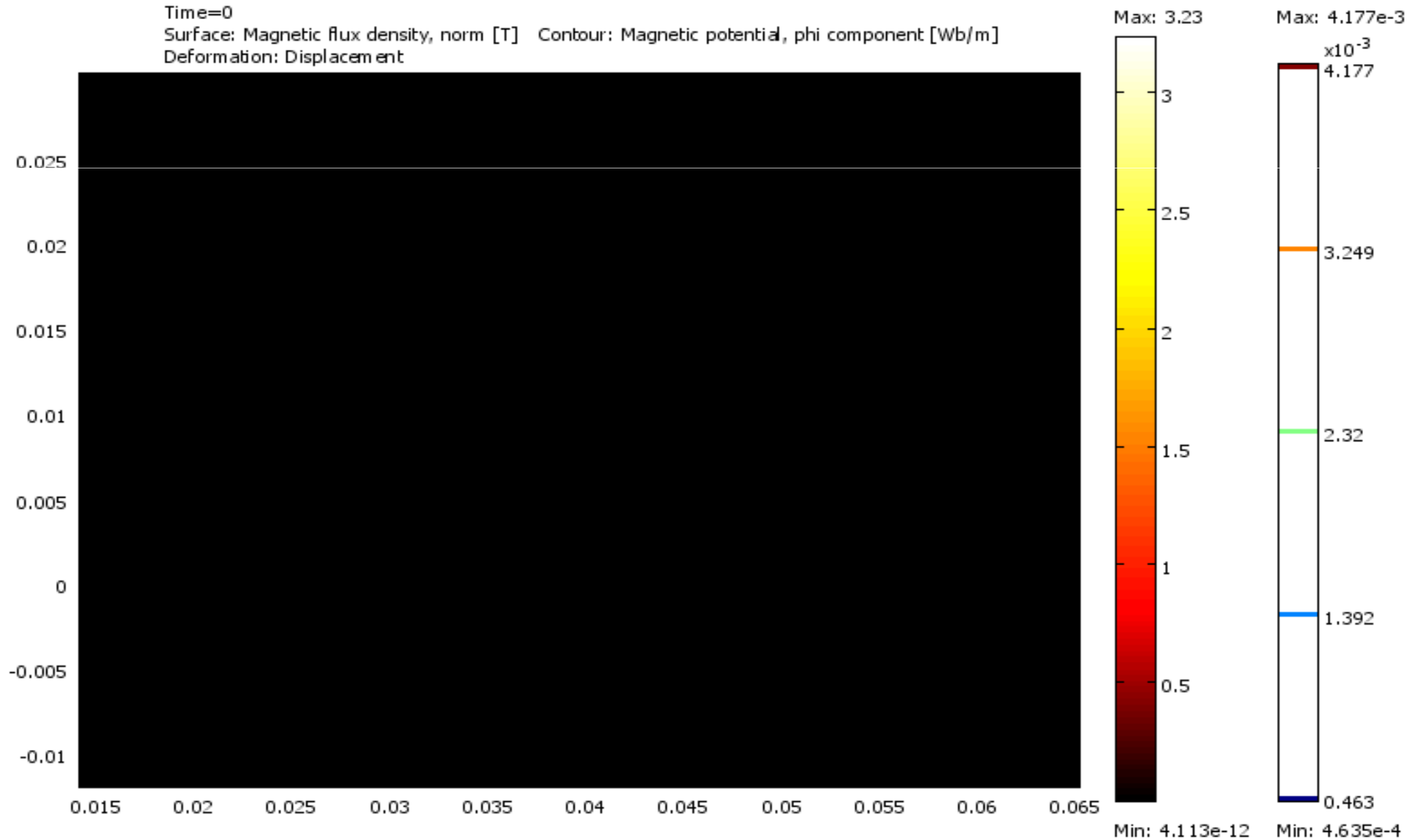
TC simulation 1



TC simulation 2

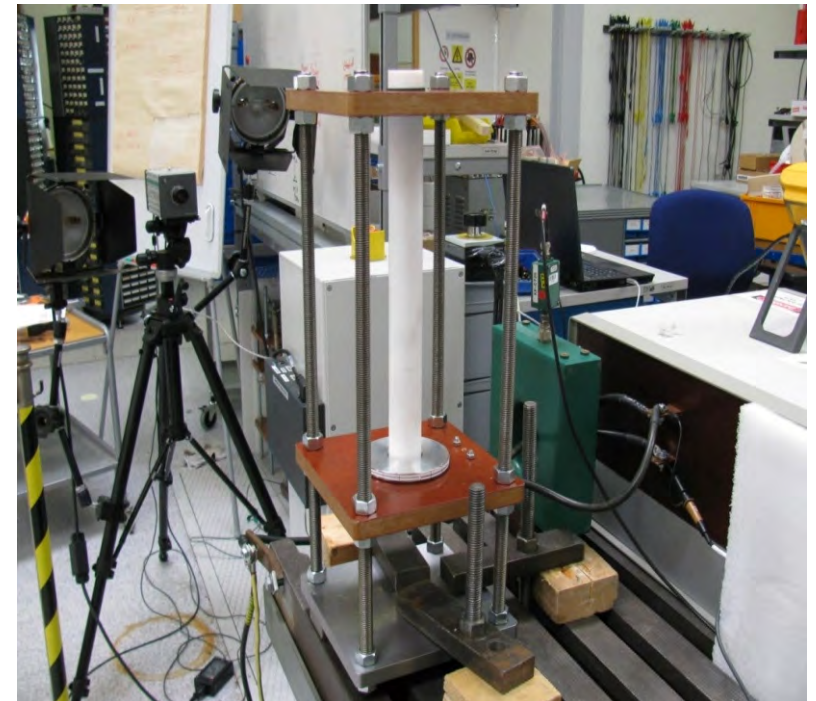
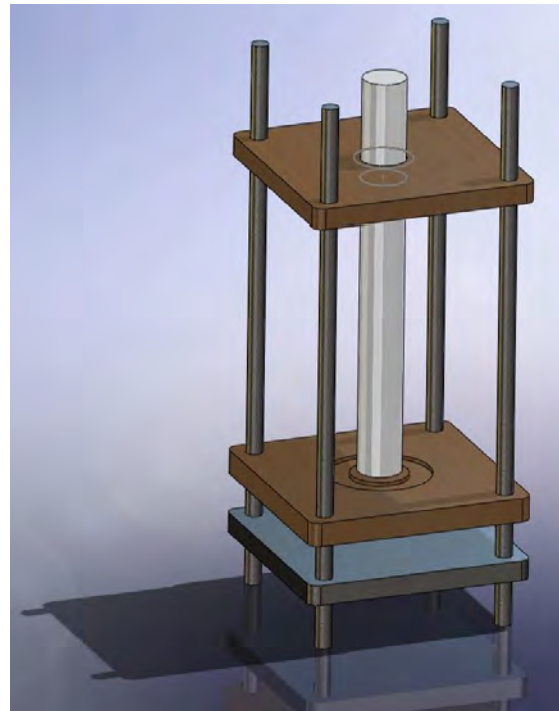
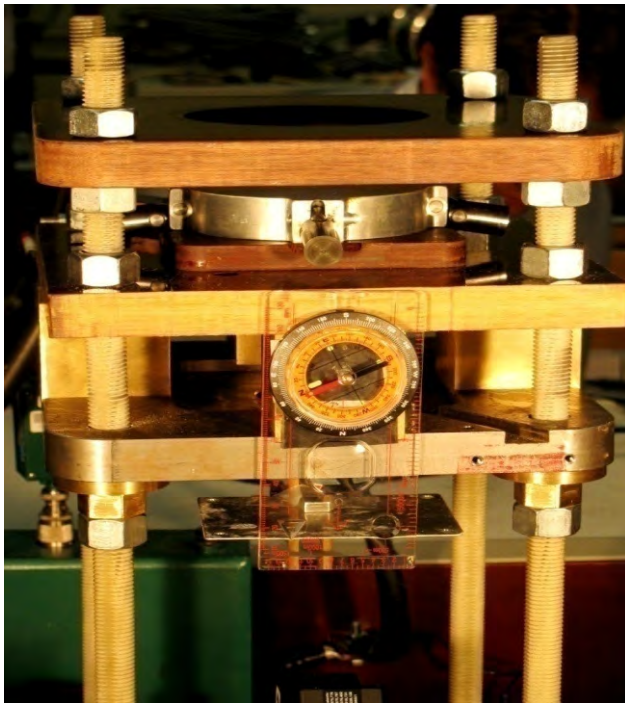


TC simulation 3



Model verification

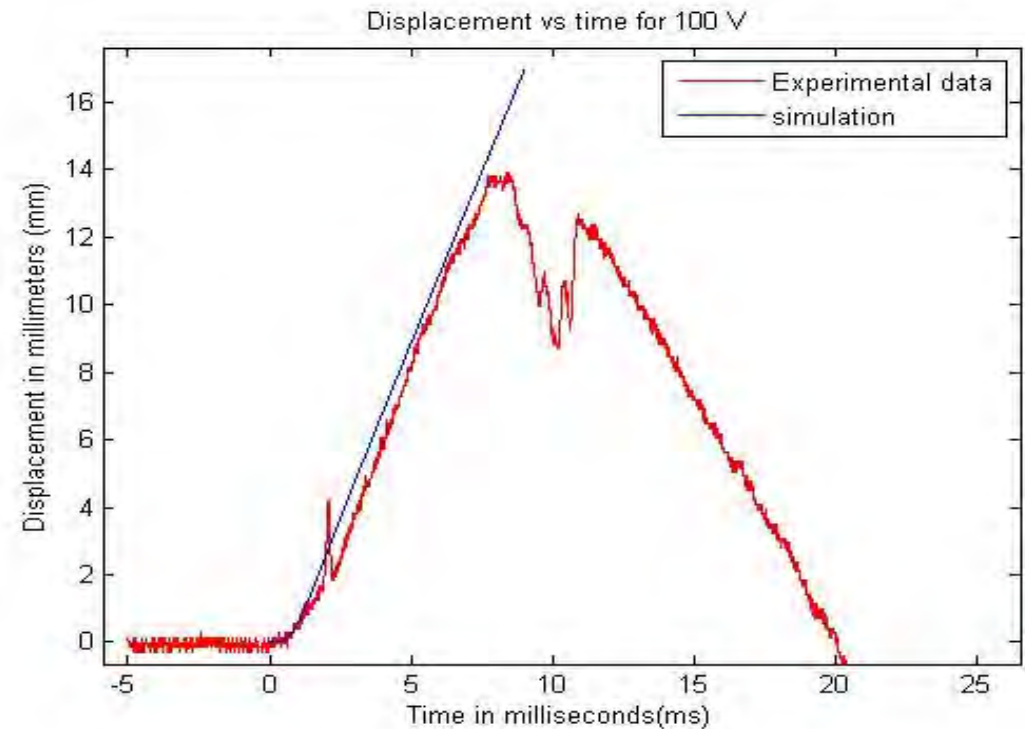
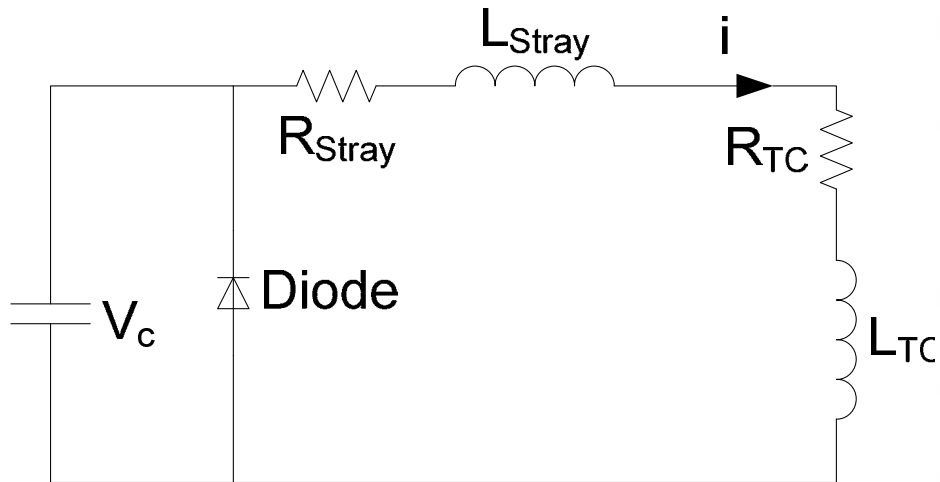
- Experimental verification is carried out to verify the results simulated in COMSOL.
- The results are compared with two experiments:
 - Experiment I was already carried out at ABB
 - Experiment II is the custom built prototype of the TC



Model verification

Exp I

| Setup Characteristics | |
|-----------------------------------|---------------|
| Capacitor bank | 33 mF |
| Initial voltage | 400 V |
| Al Cross section area | 50 mm x 20 mm |
| Coil conductor cross section area | 2 mm x 4 mm |
| Air gap between coil and Al | 1 mm |
| Number of coil turns | 10 |
| Gap between coil turns | 0.1 mm |
| Stray resistance | 10 m Ω |
| Stray inductance | 1 μ H |



Model verification

Exp 2

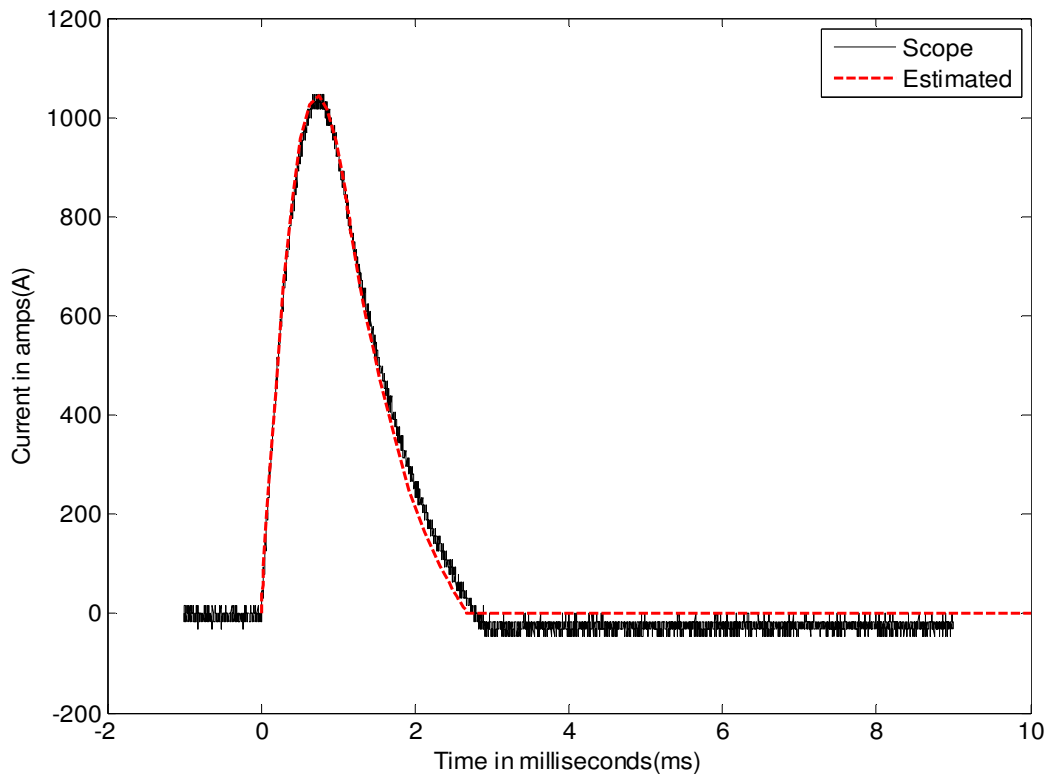
- Three series of tests were carried out:
- Test 1: The 33 mF capacitor bank is discharged in the coil with no aluminum ring on top at three voltage levels: 25, 50, and 100V
 - ❖ Aim: Determine the stray impedance
 - **Step 1:** The oscilloscope is used to measure the voltage and current pulse without any influence from the aluminum ring.
 - **Step 2:**The resistance and inductance of the coil are determined by running a COMSOL simulation with no aluminum disk.
 - **Step3:** The stray impedance can be approximated by solving for the following differential equations in MATLAB and comparing with the voltage and current waveforms measured in the lab:

Model verification

Exp 2

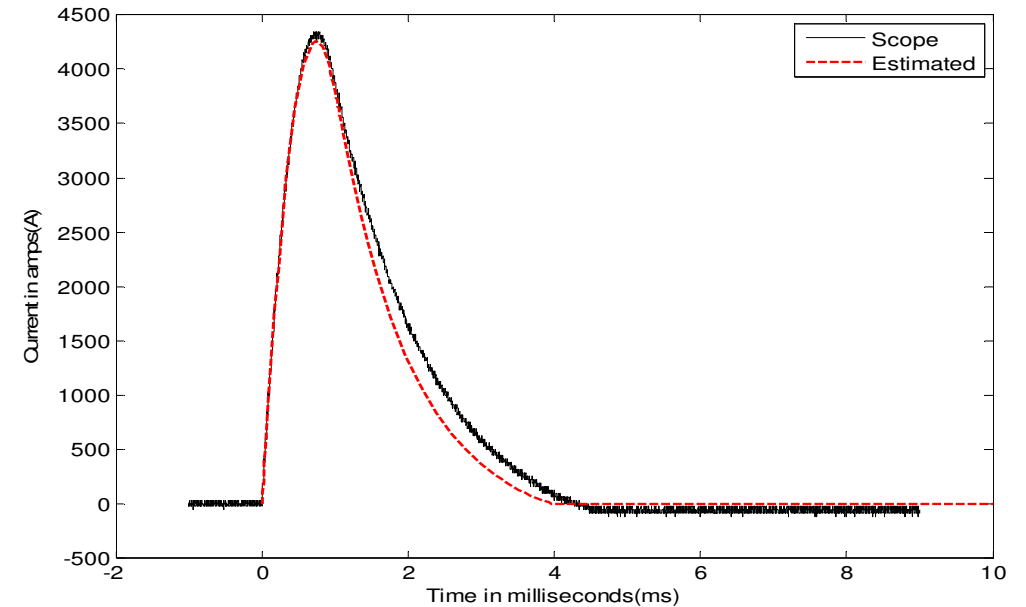
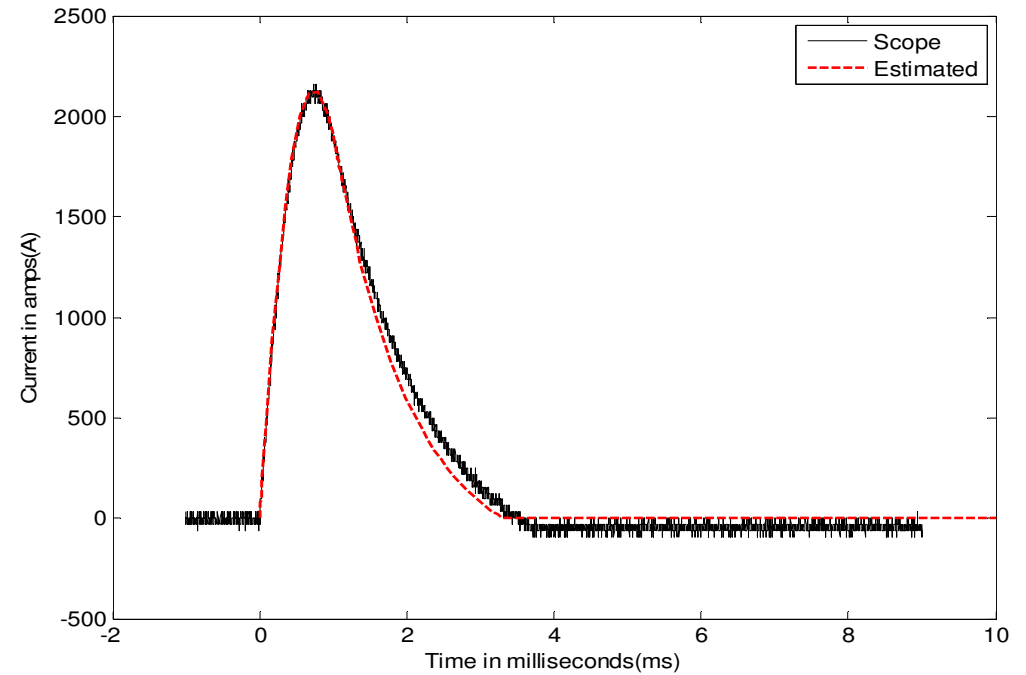
$$\frac{dV_C}{dt} = -\frac{i}{C}$$

$$\frac{di}{dt} = \frac{1}{L + L_{Stray}} (V_C - R_{Stray}i - R_{TC}i)$$



Current pulse at 25 V

Current pulse at 50 V

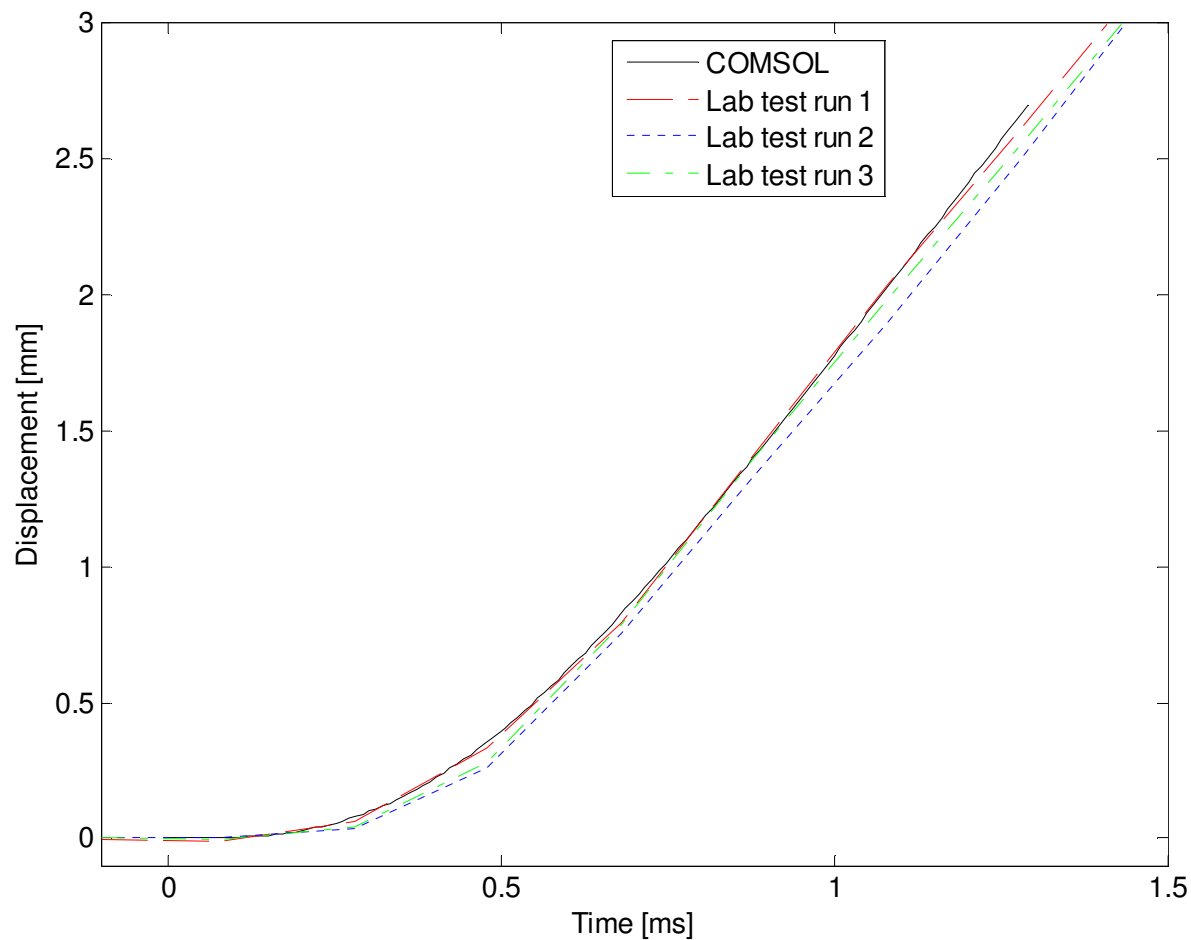


Current pulse at 100 V

Model verification

Exp 2

- Test 2: A Teflon cylinder is used to guide the aluminum ring.
- Test 3: The guide is removed to record the displacement of the aluminum disk without friction.



Model verification

Exp 2

- The sources of error are:
 - The coil is modeled as concentric rings in COMSOL and not as a spiral
 - Air resistance is neglected
 - The impedance of the coil is not 100% accurate
 - The stray impedance is not constant
 - The discharged voltage from the capacitor bank is not 100% exact
- **Conclusions:**
 - No need for a guide since the aluminum follows a straight trajectory.
 - The model predicts the exerted forces on the aluminum disk with high accuracy.

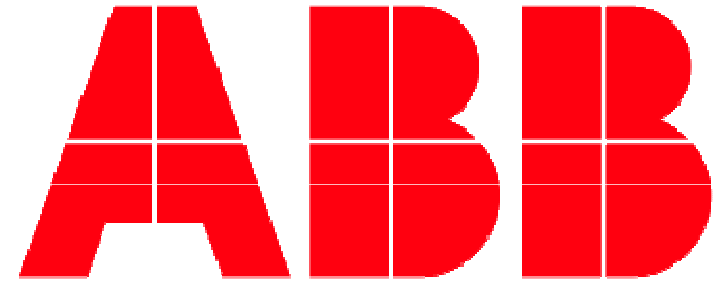
Conclusions

- Static and stationary models serve as a good start to study the behavior and characteristics of a TC at different frequencies
- A single equivalent frequency in a stationary model is not sufficient
- This experimentally validated multiphysics finite element transient model can be used to design a TC to meet the needed requirements

Movies- TC 50 V No guide, No bottom damper

Movies- TC 150 V with guide and bottom damper

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